

Analysis of Path-vector Routing Stability

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Introduction

- Border Gateway Protocol (BGP)
 - Inter-domain (AS) routing protocol of the Internet routing system
 - (AS-)Path vector routing algorithm
 - Capabilities
 - Policing (without exchange of policies)
 - Prefix and community-based traffic engineering
- Affected by instability
 - **Policy-induced instability**: conflicting policy interactions
 - **Protocol-induced instability**: path exploration
- Effects
 - Non-deterministic unstable states (dispute wheels)
 - Delayed BGP convergence (long convergence time)

Routing system/state stability

- Characterized by its response (in terms of processing of routing information) to inputs of finite amplitude
- Inputs may be classified as follows
 - **Internal events**
 - Routing protocol configuration change
 - Software changes/updates
 - **External events**
 - Topological changes
 - Policy changes

Both types of events lead to exchange of routing updates that may result in routing states changes

- Note: BGP does not differentiate routing updates with respect to their root cause, their identification (origin), etc. during its selection process

Objectives

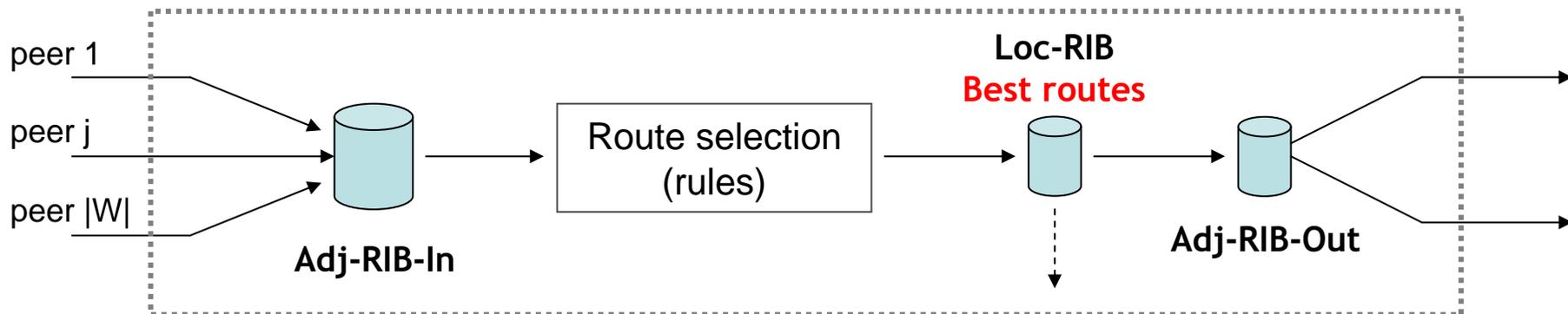
- 1) Develop a **method to systematically process** and interpret data part of BGP Routing Information Bases (RIB) to identify and characterize occurrences of BGP routing system instability
- 2) Determine a **set of stability metrics** to measure local stability properties of path-vector routing
- 3) Investigate how path-vector routing behavior and network dynamics **mutually influence** each other

By means of these metrics

- Develop a method to analyze effects/impacts of BGP policy- and protocol-induced instability on local routers.
- Derive a stability decision criterion that can be applied as part of the BGP route selection process
- Study applicability of this decision criterion using real BGP datasets

BGP and Stability Metrics

- Stability of selected route r_i at time t (Loc_RIB): $\varphi_i(t)$
- **Most stable in Adj_RIB_In**: relative stability between learned routes with identical dest. d at time $t+1$ and most stable learned route for dest d . at time t : $\Delta\varphi_{i,j}(t+1) = [\varphi_{i,j}(t+1) + 1] / [\varphi_{i,stable}(t) + 1]$
- **Best selectable route in Adj_RIB_In**: relative stability between learned routes with identical dest. d at time $t+1$ and route selected by BGP for dest d . at time t : $\Delta\varphi_{i,j}(t+1) = [\varphi_{i,j}(t+1) + 1] / [\varphi_{i,selected}(t) + 1]$
- **Differential stability** between most stable candidate route and the route currently selected by BGP: $\delta\varphi_i(t) = \varphi_{i,selected}(t) - \varphi_{i,candidate}(t)$



Differential stability

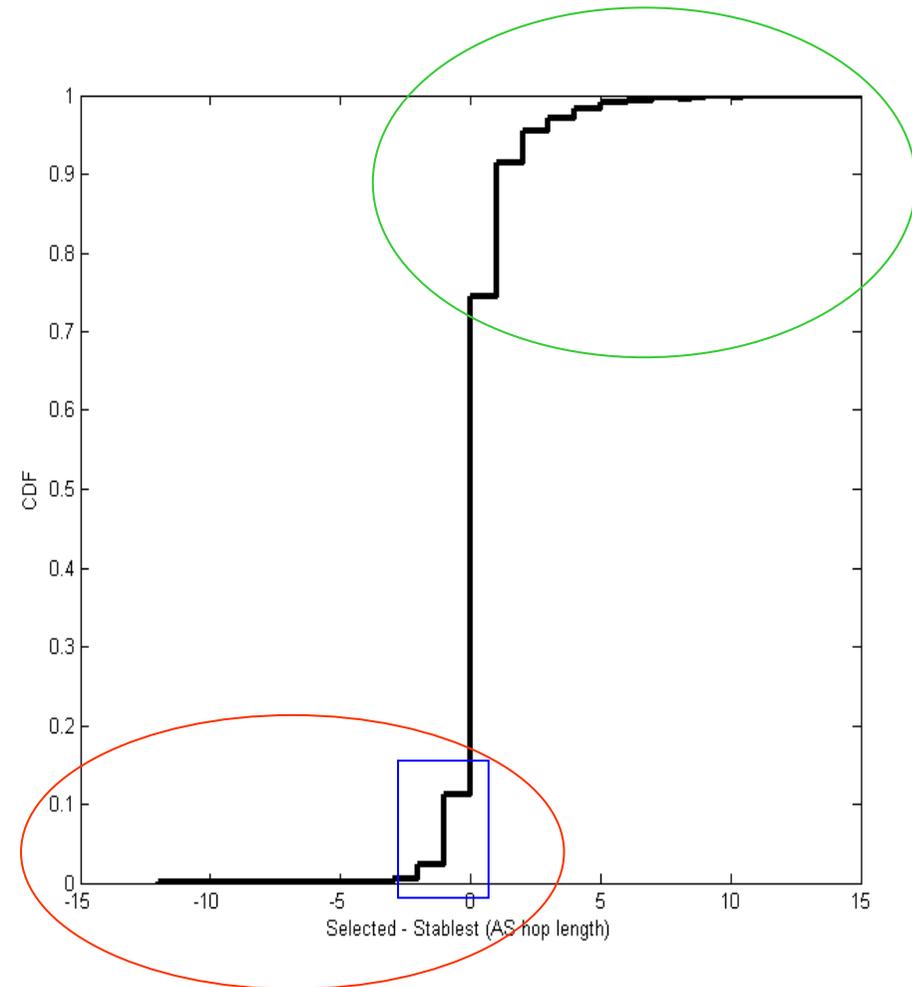
- Differential stability between selected route at time t for dest. d (stored in Loc_RIB) and newly selected route at time $t+1$ for same dest. d : $\delta\varphi_i$ ($i \in [1, |D|]$)
 - Characterizes stability of selected route $r_i(t)$ at time t (active route for dest. d) against stability of newly selected route $r_i^*(t)$ at time t for the same destination that would replace $r_i(t)$ at time $t+1$:

$$\delta\varphi_i(t) = \varphi_i(t) - \varphi_i^*(t)$$

where, $\varphi_i(t) = \varphi_{i,\text{selected}}(t)$ and $\varphi_i^*(t) = \varphi_{i,\text{candidate}}(t)$
 - If $\delta\varphi_i(t) > 0$ then replacement of route $r_i(t)$ by $r_i^*(t)$ increases stability
Otherwise, safest decision is to keep currently selected route $r_i(t)$
- Application of metric $\delta\varphi_i$ in BGP route selection
 - Prevents replacement of more stable routes by less stable one
 - Enables selection of more stable routes than currently selected routes
- Local Proof of consistency of stability-based selection with preferential-based selection (path ranking) [SIGMETRICS11]

Measurement-based Results

- Data set: routeviews BGP data set containing around 11M routes (Adj_RIBs_In)
- Stability decision criteria ($\delta\phi_i(t) > 0$) leads to AS-Path length/stretch decrease ($\delta\rho_i(t) > 0$) for more than 25% of the routes
- Using this decision criteria no negative/detrimental effects for 90% of the routes
- Only 10% of the routes would be stretch increasing ($\delta\rho_i(t) < 0$ with $\delta\phi_i(t) > 0$) but stretch increase would be limited to 1 or 2 AS-hops



Conclusion

- Differential stability-based decision criterion that can be taken into account as part of the BGP route selection process.
- A significant fraction of the routes (90%) selected by means of this process is not stretch increasing.
 - If one would admit an AS_path length increase of one AS-hop, only a minor fraction of the routes (about 2%) would be penalized by a higher stretch increase (two AS-hops and above)
- Future/ongoing work includes
 - Verify general trade-offs between stability-based route selection and resulting stretch increase/decrease factor on selected routing paths
 - Determine necessary but sufficient conditions for preventing potential oscillations to occur (as local action of selecting a more stable route shall not induce unwanted perturbation(s) on neighboring routing states)
 - Generalize formulation of stability function (and variation increments)
 - Model extended to discriminate between policy vs. protocol instability